NAG Fortran Library Routine Document

C05NDF

Note: before using this routine, please read the Users' Note for your implementation to check the interpretation of **bold italicised** terms and other implementation-dependent details.

1 Purpose

C05NDF is a comprehensive reverse communication routine to find a solution of a system of nonlinear equations by a modification of the Powell hybrid method.

2 Specification

```
SUBROUTINE CO5NDF (IREVCM, N, X, FVEC, XTOL, ML, MU, EPSFCN, DIAG, MODE, FACTOR, FJAC, LDFJAC, R, LR, QTF, W, IFAIL)

INTEGER

IREVCM, N, ML, MU, MODE, LDFJAC, LR, IFAIL

X(N), FVEC(N), XTOL, EPSFCN, DIAG(N), FACTOR, FJAC(LDFJAC,N), R(LR), QTF(N), W(N,4)
```

3 Description

The system of equations is defined as:

$$f_i(x_1, x_2, \dots, x_n) = 0, \quad i = 1, 2, \dots, n.$$

C05NDF is based upon the MINPACK routine HYBRD (see Moré *et al.* (1980)). It chooses the correction at each step as a convex combination of the Newton and scaled gradient directions. Under reasonable conditions this guarantees global convergence for starting points far from the solution and a fast rate of convergence. The Jacobian is updated by the rank-1 method of Broyden. At the starting point the Jacobian is approximated by forward differences, but these are not used again until the rank-1 method fails to produce satisfactory progress. For more details see Powell (1970).

4 References

Moré J J, Garbow B S and Hillstrom K E (1980) User guide for MINPACK-1 *Technical Report ANL-80-74* Argonne National Laboratory

Powell M J D (1970) A hybrid method for nonlinear algebraic equations *Numerical Methods for Nonlinear Algebraic Equations* (ed P Rabinowitz) Gordon and Breach

5 Parameters

Note: this routine uses **reverse communication**. Its use involves an initial entry, intermediate exits and reentries, and a final exit, as indicated by the **parameter IREVCM**. Between intermediate exits and reentries, **all parameters other than FVEC must remain unchanged**.

1: IREVCM – INTEGER

Input/Output

On initial entry: must have the value 0.

On intermediate exit: specifies what action you must take before re-entering C05NDF with IREVCM unchanged. The value of IREVCM should be interpreted as follows:

IREVCM = 1

Indicates the start of a new iteration. No action is required by you, but X and FVEC are available for printing.

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IREVCM = 2

Indicates that before re-entry to C05NDF, FVEC must contain the function values $f_i(x)$.

On final exit: IREVCM = 0, and the algorithm has terminated.

Constraint: IREVCM = 0, 1 or 2.

2: N – INTEGER

Input

On initial entry: n, the number of equations.

Constraint: N > 0.

3: X(N) – double precision array

Input/Output

On initial entry: an initial guess at the solution vector.

On intermediate exit: contains the current point.

On final exit: the final estimate of the solution vector.

4: FVEC(N) – *double precision* array

Input/Output

On initial entry: need not be set.

On intermediate re-entry: if IREVCM \neq 2, FVEC must not be changed.

If IREVCM = 2, FVEC must be set to the values of the functions computed at the current point X.

On final exit: the function values at the final point, X.

5: XTOL – double precision

Input

On initial entry: the accuracy in X to which the solution is required.

Suggested value: the square root of the machine precision.

Constraint: $XTOL \ge 0.0$.

6: ML – INTEGER

Input

On initial entry: the number of subdiagonals within the band of the Jacobian matrix. (If the Jacobian is not banded, or you are unsure, set ML = N - 1.)

Constraint: $ML \ge 0$.

7: MU – INTEGER

Input

On initial entry: the number of superdiagonals within the band of the Jacobian matrix. (If the Jacobian is not banded, or you are unsure, set MU = N - 1.)

Constraint: MU > 0.

8: EPSFCN – double precision

Input

On initial entry: the order of the largest relative error in the functions. It is used in determining a suitable step for a forward difference approximation to the Jacobian. If EPSFCN is less than **machine precision** then **machine precision** is used. Consequently a value of 0.0 will often be suitable.

Suggested value: EPSFCN = 0.0.

9: DIAG(N) - double precision array

Input/Output

On initial entry: if MODE = 2 (see below), DIAG must contain multiplicative scale factors for the variables.

Constraint: DIAG(i) > 0.0, for i = 1, 2, ..., n.

On intermediate exit: the scale factors actually used (computed internally if MODE \neq 2).

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10: MODE – INTEGER

Input

On initial entry: indicates whether or not you have provided scaling factors in DIAG. If MODE = 2 the scale factors must be supplied in DIAG. Otherwise, the variables will be scaled internally.

11: FACTOR – double precision

Input

On initial entry: a quantity to be used in determining the initial step bound. In most cases, FACTOR should lie between 0.1 and 100.0. (The step bound is FACTOR \times ||DIAG \times X||₂ if this is non-zero; otherwise the bound is FACTOR.)

Suggested value: FACTOR = 100.0.

Constraint: FACTOR > 0.0.

12: FJAC(LDFJAC,N) – *double precision* array

Input/Output

On initial entry: need not be set.

On intermediate exit: should not be changed.

On final exit: the orthogonal matrix Q produced by the QR factorization of the final approximate Jacobian.

13: LDFJAC – INTEGER

Input

On initial entry: the first dimension of the array FJAC as declared in the (sub)program from which C05NDF is called.

Constraint: LDFJAC \geq N.

14: R(LR) – *double precision* array

Input/Output

On initial entry: need not be set.

On intermediate exit: should not be changed.

On final exit: the upper triangular matrix R produced by the QR factorization of the final approximate Jacobian, stored row-wise.

15: LR – INTEGER

Input

On initial entry: the dimension of the array R as declared in the (sub)program from which C05NDF is called.

Constraint: LR $\geq N \times (N+1)/2$.

16: QTF(N) - double precision array

Input/Output

On initial entry: need not be set.

On intermediate exit: should not be changed.

On final exit: the vector $Q^{T}f$.

17: W(N,4) – *double precision* array

Communication Array

18: IFAIL – INTEGER

Input/Output

On initial entry: IFAIL must be set to 0, -1 or 1. If you are unfamiliar with this parameter you should refer to Chapter P01 for details.

On final exit: IFAIL = 0 unless the routine detects an error (see Section 6).

For environments where it might be inappropriate to halt program execution when an error is detected, the value -1 or 1 is recommended. If the output of error messages is undesirable, then the value 1 is recommended. Otherwise, because for this routine the values of the output parameters

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may be useful even if IFAIL $\neq 0$ on exit, the recommended value is -1. When the value -1 or 1 is used it is essential to test the value of IFAIL on exit.

6 Error Indicators and Warnings

If on entry IFAIL = 0 or -1, explanatory error messages are output on the current error message unit (as defined by X04AAF).

Errors or warnings detected by the routine:

```
IFAIL = 1
```

```
On entry, N \le 0,

or XTOL < 0.0,

or ML < 0,

or MU < 0,

or FACTOR \le 0.0,

or LDFJAC < N,

or LR < N \times (N+1)/2,

or MODE = 2 and DIAG(i) \le 0.0 for some i, i = 1, 2, ..., N.
```

IFAIL = 2

On entry, IREVCM < 0 or IREVCM > 2.

IFAIL = 3

No further improvement in the approximate solution X is possible; XTOL is too small.

IFAIL = 4

The iteration is not making good progress, as measured by the improvement from the last 5 Jacobian evaluations.

IFAIL = 5

The iteration is not making good progress, as measured by the improvement from the last 10 iterations.

The values IFAIL = 4 and IFAIL = 5 may indicate that the system does not have a zero, or that the solution is very close to the origin (see Section 7). Otherwise, rerunning C05NDF from a different starting point may avoid the region of difficulty.

7 Accuracy

If \hat{x} is the true solution and D denotes the diagonal matrix whose entries are defined by the array DIAG, then C05NDF tries to ensure that

$$||D(x-\hat{x})||_2 \leq \text{XTOL} \times ||D\hat{x}||_2.$$

If this condition is satisfied with $XTOL = 10^{-k}$, then the larger components of Dx have k significant decimal digits. There is a danger that the smaller components of Dx may have large relative errors, but the fast rate of convergence of C05NDF usually avoids this possibility.

If XTOL is less than *machine precision* and the above test is satisfied with the *machine precision* in place of XTOL, then the routine exits with IFAIL = 3.

Note that this convergence test is based purely on relative error, and may not indicate convergence if the solution is very close to the origin.

The test assumes that the functions are reasonably well behaved. If this condition is not satisfied, then C05NDF may incorrectly indicate convergence. The validity of the answer can be checked for example, by rerunning C05NDF with a tighter tolerance.

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8 Further Comments

The time required by C05NDF to solve a given problem depends on n, the behaviour of the functions, the accuracy requested and the starting point. The number of arithmetic operations executed by C05NDF to process the evaluation of functions in the main program in each exit is about $11.5 \times n^2$. The timing of C05NDF will be strongly influenced by the time spent in the evaluation of the functions.

Ideally the problem should be scaled so that, at the solution, the function values are of comparable magnitude.

The number of function evaluations required to evaluate the Jacobian may be reduced if you can specify ML and MU.

9 Example

To determine the values x_1, \ldots, x_9 which satisfy the tridiagonal equations:

$$(3-2x_1)x_1-2x_2 = -1,$$

$$-x_{i-1} + (3-2x_i)x_i - 2x_{i+1} = -1, i = 2, 3, ..., 8$$

$$-x_8 + (3-2x_9)x_9 = -1.$$

9.1 Program Text

```
CO5NDF Example Program Text
   Mark 14 Release. NAG Copyright 1989.
   .. Parameters ..
   INTEGER
                   N, LDFJAC, LR
   PARAMETER
                    (N=9,LDFJAC=N,LR=(N*(N+1))/2)
   TNTEGER
                   NOUT
   PARAMETER
                    (NOUT=6)
  DOUBLE PRECISION ONE, TWO, THREE
                  (ONE=1.0D0,TWO=2.0D0,THREE=3.0D0)
  PARAMETER
   .. Local Scalars ..
   DOUBLE PRECISION EPSFCN, FACTOR, FNORM, XTOL
                    ICOUNT, IFAIL, IREVCM, J, K, ML, MODE, MU
   INTEGER
   .. Local Arrays ..
  DOUBLE PRECISION DIAG(N), FJAC(LDFJAC,N), FVEC(N), QTF(N), R(LR),
                    W(N,4), X(N)
   .. External Functions ..
  DOUBLE PRECISION FO6EJF, X02AJF
  EXTERNAL
                   FO6EJF, XO2AJF
   .. External Subroutines ..
   EXTERNAL
                   C05NDF
   .. Intrinsic Functions ..
   INTRINSIC
               SQRT
   .. Executable Statements ..
   WRITE (NOUT,*) 'CO5NDF Example Program Results'
   The following starting values provide a rough solution.
   DO 20 J = 1, N
      X(J) = -1.0D0
20 CONTINUE
   XTOL = SQRT(XO2AJF())
   DO 40 J = 1, N
     DIAG(J) = 1.0D0
40 CONTINUE
  ML = 1
  MU = 1
  EPSFCN = 0.0D0
   MODE = 2
   FACTOR = 100.0D0
   ICOUNT = 0
   IFAIL = 1
  IREVCM = 0
60 CALL CO5NDF(IREVCM,N,X,FVEC,XTOL,ML,MU,EPSFCN,DIAG,MODE,FACTOR,
               FJAC, LDFJAC, R, LR, QTF, W, IFAIL)
   IF (IREVCM.EQ.1) THEN
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```
ICOUNT = ICOUNT + 1
          Insert print statements here to monitor progess if desired.
          GO TO 60
      ELSE IF (IREVCM.EQ.2) THEN
         Evaluate functions at given point
         DO 80 K = 1, N
             FVEC(K) = (THREE-TWO*X(K))*X(K) + ONE
             IF (K.GT.1) FVEC(K) = FVEC(K) - X(K-1)
IF (K.LT.N) FVEC(K) = FVEC(K) - TWO*X(K+1)
   80
          CONTINUE
          GO TO 60
      END IF
      WRITE (NOUT, *)
      IF (IFAIL.EQ.O) THEN
          FNORM = FO6EJF(N, FVEC, 1)
          WRITE (NOUT,99999) 'Final 2-norm of the residuals after', ICOUNT, ' iterations is ', FNORM
          WRITE (NOUT, *)
          WRITE (NOUT,*) 'Final approximate solution'
          WRITE (NOUT, 99998) (X(J), J=1, N)
      ELSE
          WRITE (NOUT, 99999) 'IFAIL =', IFAIL
          IF (IFAIL.GE.2) THEN
             WRITE (NOUT,*) 'Approximate solution'
             WRITE (NOUT, 99998) (X(J), J=1, N)
          END IF
      END IF
      STOP
99999 FORMAT (1X,A,I4,A,E12.4)
99998 FORMAT (5X,3F12.4)
      END
```

9.2 Program Data

None.

9.3 Program Results

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